# COL874 Advanced Compiler Techniques

Modules 141-145

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## Lec-141: Affine Space Partitions



- Data dependencies exist across different iterations of the first loop
- Possible to transform the axes of the program to exploit Synchronization Free
   Parallelization
- Iterations of the outer loop in the transformed program can be done in parallel
- Why? Because there are no data dependencies across different values of k
- Increased locality due to the transformation as we decrease the reuse distance

## Data Dependence Constraints

- If these constraints yield No Solution, then there is no data dependence across different values of *k* for the given pair of static accesses
- Check this for all possible pairs of static accesses (including self pairings)
- If the conditions are satisfied: <u>the loop</u> <u>has 1 degree of parallelism</u> (1 level of loop nest that can be parallelized)

# Degrees of parallelism

- A loop nest has k degrees of parallelism if it has, within the nest, k parallelizable *for* loops
- Can create O(n<sup>k</sup>) parallel <u>virtual processors</u>

2 degrees of parallelism

# Affine Space Partitions



- $l \ge k$ : it is a many-to-one map, and a function (maps all the iterations)
- Need to use as many as (virtual) processors
- Partition: All the iterations in the partition are mapped to the same processor
- Constraint: This map needs to be an affine function

# Affine Space Partitions

- Can have O(2n) virtual processors
- Our analysis should be able to exploit this
- Each 3AC statement (static access) is analyzed separately for maximum parallelism

## Lec-142: Space Partition Constraints



pid = Ci + c

- (C, c) are different for each statement s
- Variation: Could have a piecewise affine function instead of an affine function
- Piecewise affine functions can be solved using polyhedral analysis (potentially giving better results)
- Tradeoff: Performance vs Cost
- Restrict ourselves to Affine functions

# Space Partition Constraints

- Need to find a solution to (C, c) satisfying data dependency constraints
- Trivial Solution:  $C = (0 \ 0 \ \dots 0)$  and c = (0)
- Represents a zero-dimensional processor space
- Everything mapped to the same processor
- Valid solution but not very useful due to no parallelism
- Also need to maximize the processor space dimension / rank of C
- Affine Partition: a (C, c) solution for each statement s represents an <u>Affine</u> <u>partition</u>

### Space Partition Constraints

For 
$$S_1 = (F_1, f_1, B_1, b_1)$$
 and  $S_2 = (F_2, f_2, B_2, b_2)$ ,  
the partitions  $C_1, c_1$  and  $C_2, c_2$  must be  
such that:  
For all  $\underline{i}_1 \in \mathbb{Z}^{d_1}$  and  $i_2 \in \mathbb{Z}^{d_2}$   
 $F_1 + b_1 \ge 0$   $B_2 \underline{i}_2 + b_2 \ge 0$   
 $F_1 + f_1 = F_2 \underline{i}_2 + f_2$   
(where we there is a date dependent)  
then  $C_1 \underline{i}_1 + C_1 = C_2 \underline{i}_2 + C_2$ 

- Data dependent iterations are mapped to the same processor
- Unknowns:  $C_1, c_1, C_2, c_2$

## Space Partition Constraints



- Data dependence could be across the same statement or different statements
- Chose these unknowns such that the constraints are satisfied, and the ranks are maximized

## Lec-143: Maximum Rank Affine Partition

 Affine Partitions help us to argue about the processors, iterations and the data in a homogeneous way



- Trivial Solution:  $C_1 = \underline{0}, c_1 = \underline{0}, C_2 = \underline{0}, c_2 = \underline{0}$
- But no parallelism

# Maximum Rank Affine Partition

• Max Rank Solution:



- Desirable, but may not satisfy Data dependency constraints
- Interested in the Max Rank solution satisfying the data dependence constraints

## Max Rank constraints

For k statements 
$$S_1, S_2, ..., S_k$$
, choose  $(C_1, c_1)$   
 $(C_2, c_2), ..., (C_k, c_k)$  of maximum rank  
such that for every pair of statements  $S_2, S_b$   
 $\forall ia \in \mathbb{Z}^{da}, ib \in \mathbb{Z}^{db}$   
 $\forall Baia + ba \ge 0$   $B_b ib + b_b \ge 0$   
 $Faia + fa = F_b ib + fb$   
then  $Caia + Ca = C_b ib + Cb$ 

# Space Partitioning Example

• Running Example:

- Six Statements (one for each access); two writes
- Data dependences:
  - $X[i, j] \leftrightarrow X[i, j]$  (both R/W)
  - $X[i, j] \leftrightarrow X[i, j-1]$
  - $Y[i, j] \leftrightarrow Y[i, j]$  (both R/W)
  - $Y[i, j] \leftrightarrow Y[i-1, j]$

# Space Partitioning Example

- X[i, j] with itself won't have any space partitioning because [i, j] is a full rank access
- X[i, j] = X[i, j] + Y[i-1, j]: we do have a data dependency, but in the same iteration
- No meaningful constraints
- We need only 2 affine functions, one for each C-statement (based on scalar dependencies)

# Space Partitioning Example



- All the dependent iterations should be mapped to the same processor
- Disjoint chains are formed
- Could map each of the chains to a separate processor
- Need to find  $C_1$ ,  $c_1$ ,  $c_2$ ,  $c_2$  such that each chain is mapped to the same processor
- Answer: 1-D mapping for each statement
  - $P_1 = i j 1$  for  $s_1$
  - $P_2 = i j$  for  $s_2$

## Lec-144: Space Partition Constraints Example

- Only data dependencies:
  - $X[i, j] \leftrightarrow X[i, j-1](l)$
  - $Y[i-1, j] \leftrightarrow Y[i, j]$  (11)
- 12 unknowns



- Could use previous knowledge that dimensionality of the processor space = 1 ( $C_1$ ,  $C_2$  have dependent rows)
- For now, assume that  $C_{121} = C_{122} = 0 = C_{221} = C_{222}$

## Space Partition Constraints Example

• New Problem:

$$C_{1} = \begin{pmatrix} C_{11} & C_{12} \end{pmatrix} \qquad C_{1} = (c_{1}) \\ C_{2} = \begin{pmatrix} C_{21} & C_{22} \end{pmatrix} \qquad C_{2} = (c_{2}) \end{pmatrix}$$

# Space Partitioning Constraints

• For dependency (I):



- Possible Solution:  $C_{11} = C_{21} = 1$ ,  $C_{12} = C_{22} = 0$ ,  $c_1 = c_2 = 0$
- Iteration (i, j) is mapped to processor i
- All conditions are satisfied (one of the possible solutions)
- But this is not the only constraint

# Space Partitioning Constraints

• For dependency (II):

9 
$$f \leq i \leq 100$$
  $1 \leq j \leq 100$   
 $1 \leq i' \leq 100$   $1 \leq j' \leq 100$   
 $i-1 = i'$   $j=j'$   
Then  $(C_{11} C_{12}) \begin{pmatrix} i \\ j \end{pmatrix} + C_{12} = (C_{21} C_{22}) \begin{pmatrix} i' \\ j' \end{pmatrix} + C_{2}$ 

- Possible Solution:  $C_{11} = C_{21} = 0$ ,  $C_{12} = C_{22} = 1$ ,  $c_1 = c_2 = 0$
- This solution satisfies the second dependency but not the first
- Previous solution does not satisfy this dependency
- Need a solution that satisfies both the constraints

## Space Partitioning Example Solution

• Solution: 
$$C_{11} = C_{21} = 1$$
,  $C_{12} = C_{22} = -1$ ,  $c_1 = -1$ ,  $c_2 = 0$   
 $i - j - 1 = i' - j'$ 

• This holds for both the constraints

#### Lec-145: Solving Space Partition Constraints



- Both these constraints must be satisfied
- *i, j, i', j'* are not unknowns

- Use gaussian elimination to get rid of some variables
- Use the constrains to eliminate *i'*, *j'*



• Rewrite the equations:

$$\begin{pmatrix} (C_{11} - C_{21}) & (C_{12} - C_{22}) \\ + & C_{1} - & C_{22} - & C_{2} = 0 \end{pmatrix}$$

$$((C_{11}-C_{21}) (C_{12}-C_{22}))(i)$$
  
+  $C_{1} + C_{21} - C_{2} = 0$ 

- Overapproximate the behavior of iteration variables for these constraints
- Assume that the equations hold for all real values of *i*, *j*
- Which means that the coefficient of *i*, *j* and the constant term are zero

$$C_{11} = C_{21}$$
  

$$C_{12} = C_{22}$$
  

$$c_1 = c_2 + C_{22}$$
  

$$c_1 = c_2 - C_{22}$$

• On solving, we get:

$$-C_{12} = -C_{22} = C_{21} = C_{11} = C$$
$$c_1 = c_2 - C$$

- Actual constant values don't matter because they only shift the space of processor IDs
- WLOG, pick *C* = 1, *c*<sub>2</sub> = 0
- So, we get the same solution as before
  - $P_1 = i j 1$
  - $P_2 = i j$
- Remaining: we need to make sure that all the iterations mapped to the same processor preserve the relative order of execution of these iterations

# Thank You!

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